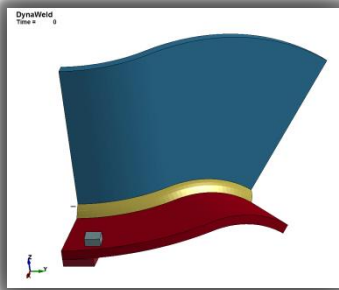
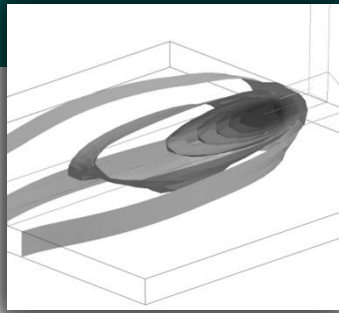




*BOUNDARY_THERMAL_WELD_TRAJECTORY



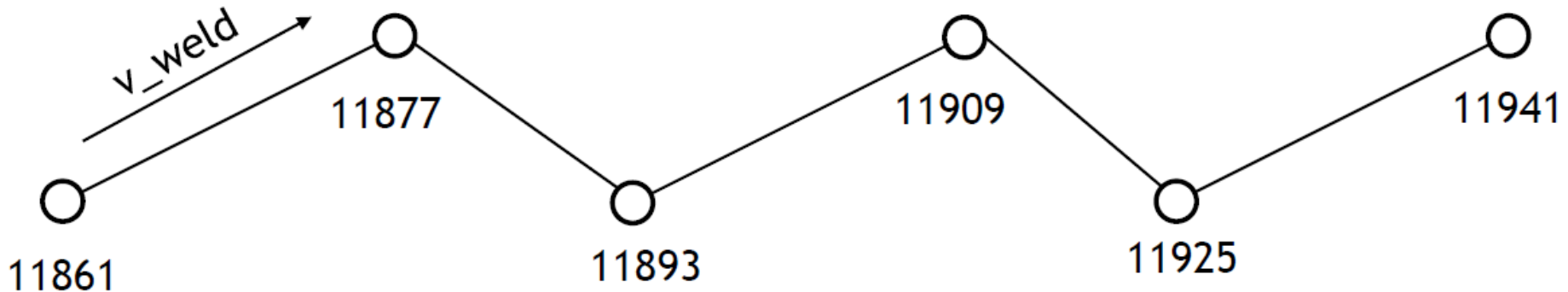
Dr.-Ing. Thomas Klöppel

DYNAmore GmbH

A new heat source - Approach

- Move the heat source movement to a new keyword.
- The heat source follows a prescribed velocity along a node path (*SET_NODE)
- The weldpath is continuously updated
- No need to include the mechanical solver

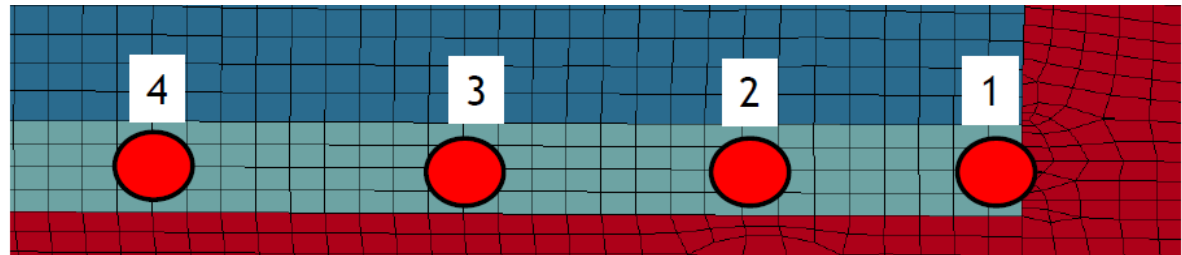
```
*SET_NODE_LIST  
1  
11861,11877,11893,11909,11925,11941
```



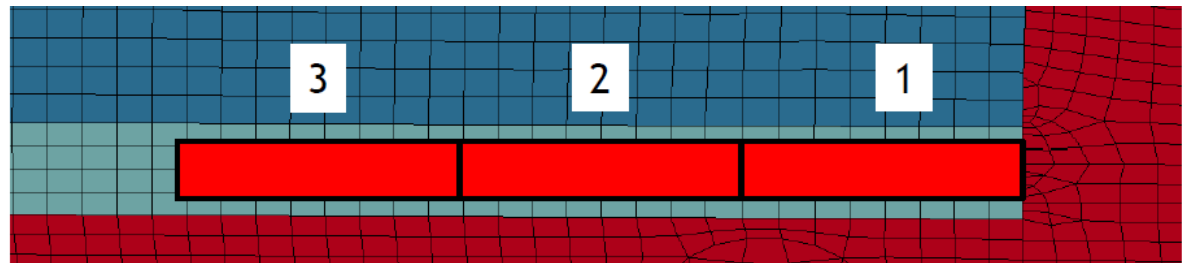
A new heat source - Approach

- Move the heat source movement to new keyword.
- The heat source follows a prescribed velocity along a nodepath
- The weldpath is continuously updated
- No need to include the mechanical solver
- Use “sub-timestep” for integration of heat source

Weld source evaluated at thermal timesteps



Weld source integrated between thermal time steps



*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

- **NSID1:** Node set ID defining the trajectory
- **VEL1:** Velocity of weld source on trajectory
 - LT.0: |VEL1| is load curve ID for velocity vs. time
- **SID2:** Second set ID for weld beam direction
 - GT.0: S2ID is node set ID, beam is aimed from these reference nodes to trajectory
 - EQ.0: beam aiming direction is (Tx, Ty, Tz)
 - LT.0: SID2 is segment set ID, weld source is orthogonal to the segments
- **VEL2:** Velocity of reference point for SID2.GT.0
- **NCYC:** number of sub-cycling steps

*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

- **IFORM:** Geometry for energy rate density distribution
 - EQ.1. Goldak-type heat source
 - EQ.2. double ellipsoidal heat source with constant density
 - EQ.3. double conical heat source with constant density
 - EQ.4. conical heat source

*BOUNDARY_THERMAL_WELD_TRAJECTORY

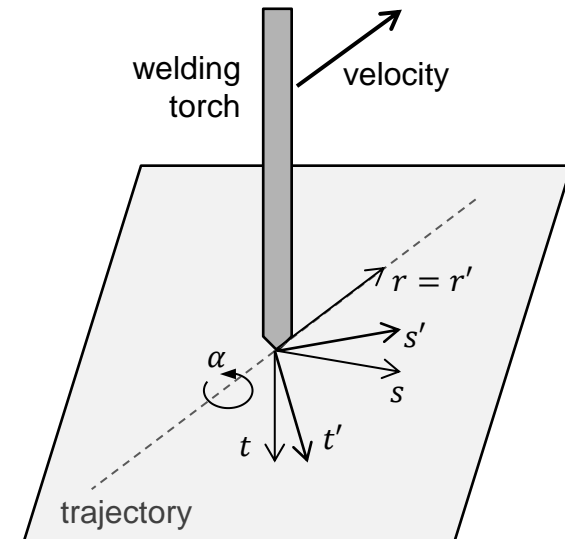
	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

- **LCID:** Load curve ID for weld energy input rate vs. time
 - EQ.0: use constant multiplier value Q
- **Q:** Curve multiplier for weld energy input
 - LT.0: use absolute value and accurate integration of heat
- **DISC:** Resolution for accurate integration. Edge length for cubic integration cells
 - Default: $0.05 * (\text{weld source depth})$

*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

- **LCROT:** load curve defining the rotation (α in degree) of weld source around the trajectory as function of time.
- **LCMOV:** load curve for offset of weld source in depth (t') after rotation as function of time
- **LCLAT:** load curve for lateral offset (s') after rotation as function of time

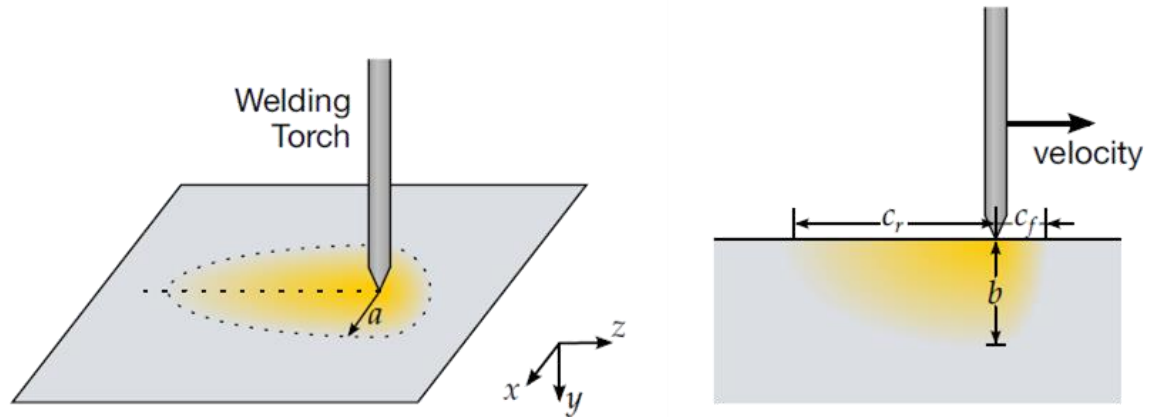


*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

■ For IFORM=1

- P1: a
- P2: b
- P3: c_f
- P4: c_r
- P5: F_f
- P6: F_r
- P7: n



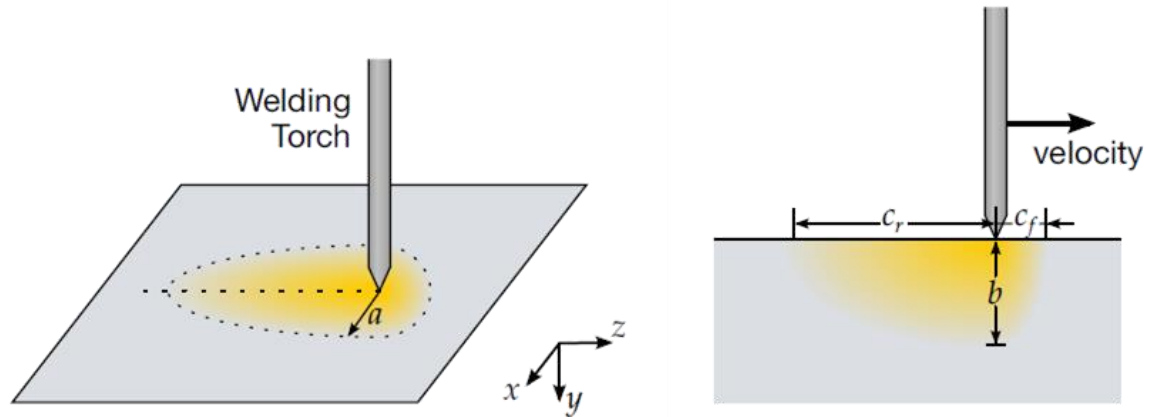
$$q = \frac{2n\sqrt{n}FQ}{\pi\sqrt{\pi}abc} \exp\left(\frac{-nx^2}{a^2}\right) \exp\left(\frac{-ny^2}{b^2}\right) \exp\left(\frac{-nz^2}{c^2}\right)$$

*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

■ For IFORM=2

- P1: a
- P2: b
- P3: c_f
- P4: c_r
- P5: F_f
- P6: F_r



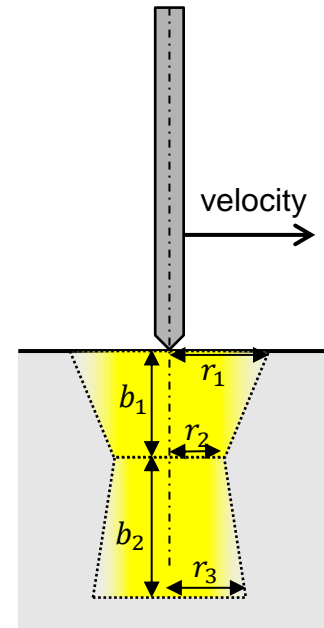
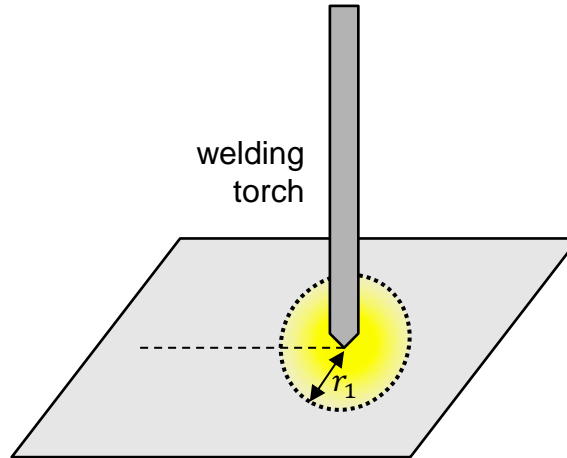
$$q = \frac{3F}{2\pi abc}$$

*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

■ For IFORM=3

- P1: r_1
- P2: r_2
- P3: r_3
- P4: b_1
- P5: b_2
- P6: F_1
- P7: F_2



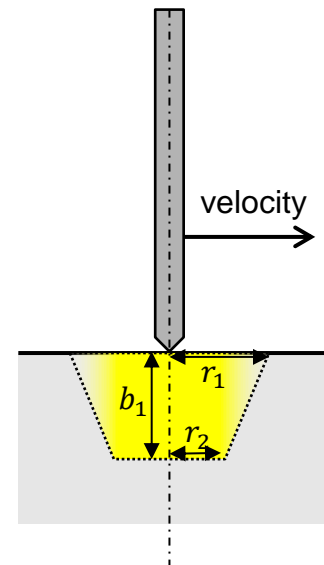
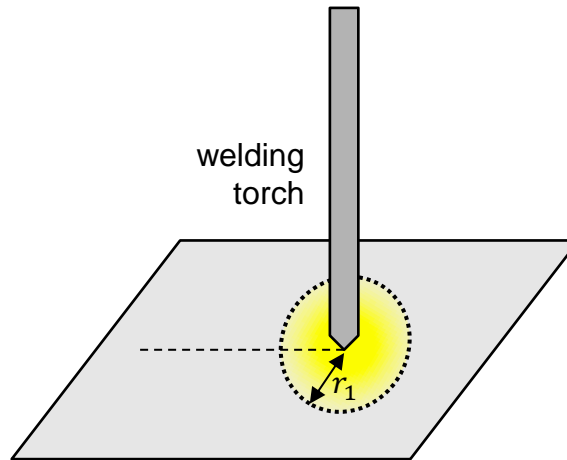
$$q = \frac{3F}{2\pi b(R^2 + r^2 + Rr)}$$

*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

■ For IFORM=4

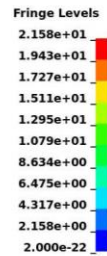
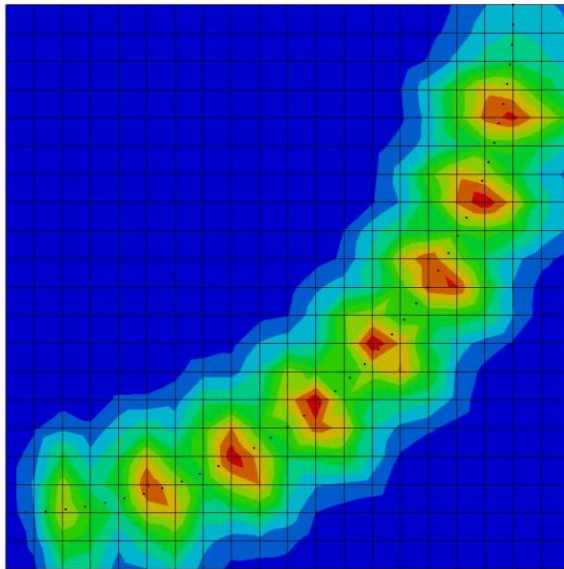
- P1: r_1
- P2: r_2
- P3: b_1



$$q = \frac{3}{\pi b (R^2 + r^2 + Rr)}$$

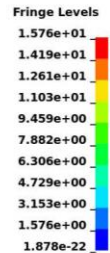
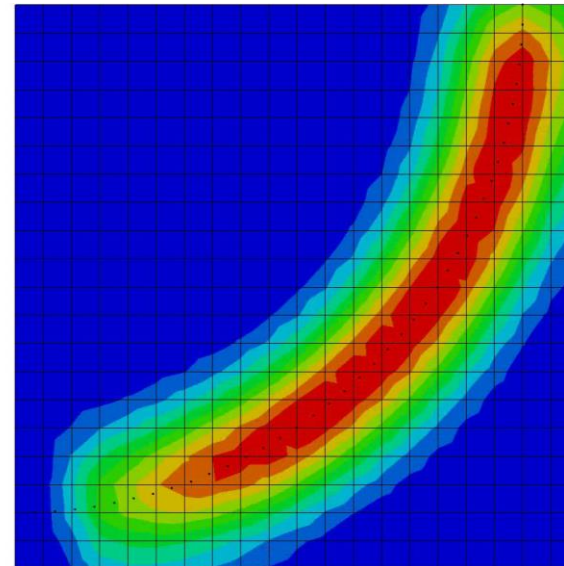
Example

- Welding on a circular trajectory
 - Thermal-only analysis with a large time step



temperature field, NCYC = 1

temperature field, NCYC = 10



Example

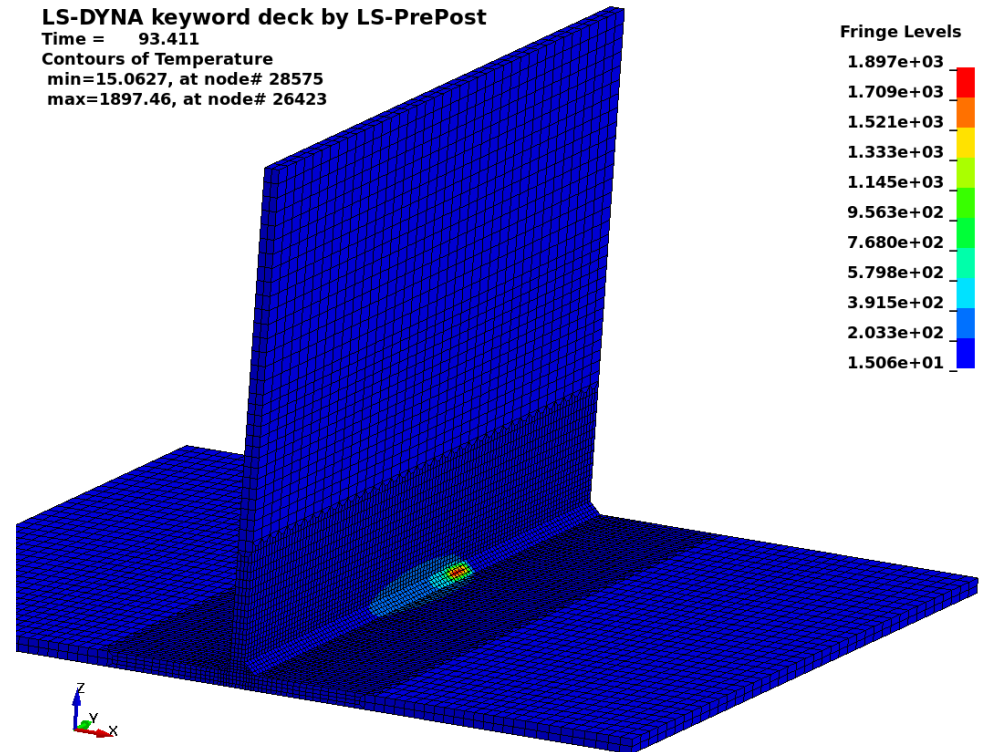
■ Three-dimensional T-Joint

- Thermal-only analysis with different values of NSUB
- Testing DISC = 0.2175 (default) and DISC = 0.5, the difference in energy input and developing temperature field are insignificant.

■ Simulation times:

NSUB	DISC=0.2175	DISC=0.5
1	20:17	12:47
2	21:02	10:43
3	23:58	08:47
4	39:23	11:28

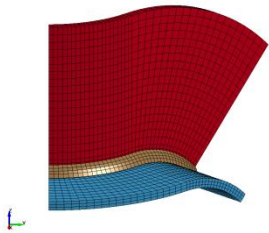
LS-DYNA keyword deck by LS-PrePost
Time = 93.411
Contours of Temperature
min=15.0627, at node# 28575
max=1897.46, at node# 26423



Example

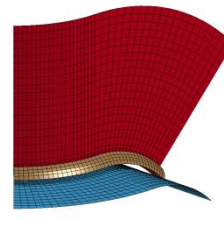
- New Keyword is also applicable to thermal thick shells
- Three-dimensional curved T-Joint, thermal-only analysis

LS-DYNA keyword deck by LS-PrePost
Time = 0



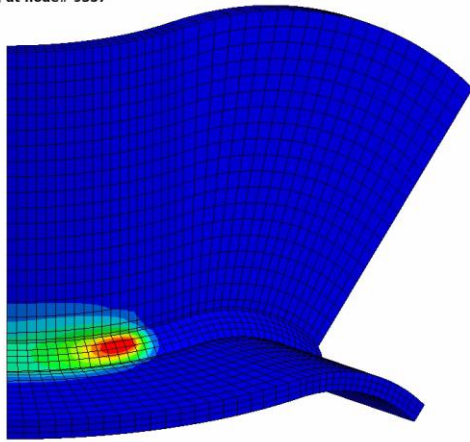
Solids

LS-DYNA keyword deck by LS-PrePost
Time = 0



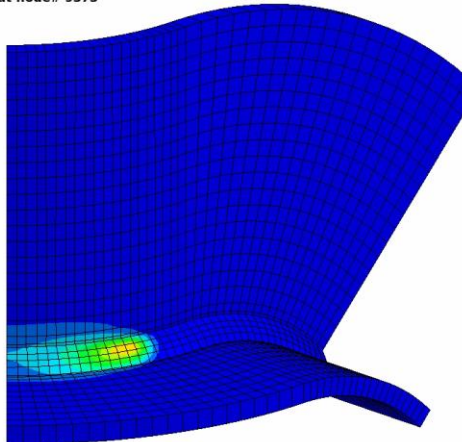
Solids and shells

LS-DYNA keyword deck by LS-PrePost
Time = 0.99484
Contours of Temperature, outer
min=19.9881, at node# 9540
max=153.564, at node# 9357



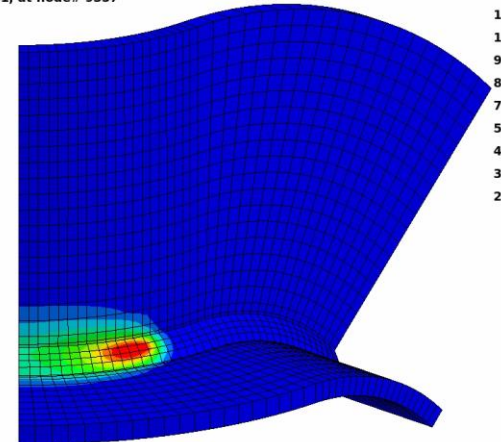
BC on all solids

LS-DYNA keyword deck by LS-PrePost
Time = 0.99484
Contours of Temperature, outer
min=19.9777, at node# 9535
max=123.47, at node# 9373



BC on solids only

LS-DYNA keyword deck by LS-PrePost
Time = 0.99484
Contours of Temperature, outer
min=19.9634, at node# 9535
max=154.901, at node# 9357



BC on solids and shells

