

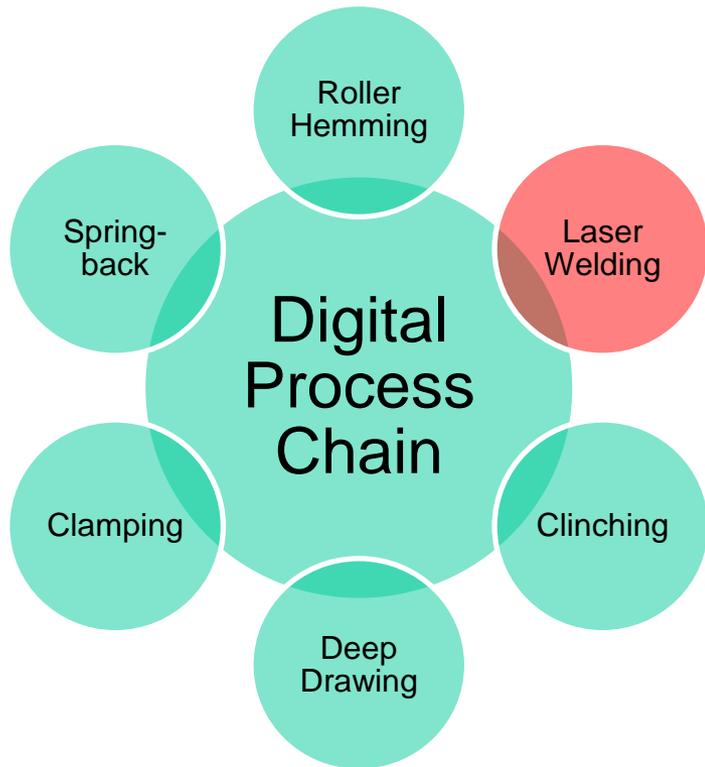
Neue Funktionalitäten in LS-DYNA für die Simulation von Schweißprozessen und Wärmebehandlung

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Infotag Schweißen und Wärmebehandlung
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Motivation - Conclusions



- Need a powerful multi-physics solver to simulate the welding process
- As stand-alone process welding is most often simulated with solid discretizations
- In automotive industries, welding is only one stage in the process chain
 - Seamless transition of data from one stage to the next
 - Typically, forming and spring-back analyses are done using shell discretizations
- All new developments are to be done for solid and shells!

CONTENT

- Motivation
- Flexible heat source definition
- Material formulations for welding simulations
- New contact options in LS-DYNA
- Conclusion

CONTENT

- Motivation

- Flexible heat source definition
 - *BOUNDARY_THERMAL_WELD
 - *BOUNDARY_THERMAL_WELD_TRAJECTORY

- Material formulations for welding simulations

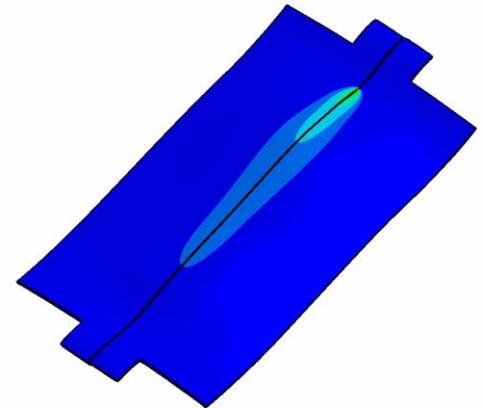
- New contact options in LS-DYNA

- Conclusion

*BOUNDARY_THERMAL_WELD

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NID	NFLAG	X0	Y0	Z0	N2ID
Card 2	a	b	cf	cr	LCID	Q	Ff	Fr
Opt.	Tx	Ty	Tz					

- Defines a Goldak type heat source
- Weld source motion possible, follows motion of node NID
 - Structure solver necessary
 - Weld path definition not straight-forward for curve geometries
 - How to compensate for part deformation due to welding itself?
- Only applicable to solid parts
- Incremental heating may lead to element distortion



Need a more flexible and easier to use boundary condition for welding!

A new heat source - approach

- move the heat source motion to a new thermal keyword
- the heat source follows a node path (*SET_NODE) with a prescribed velocity
 - no need to include the mechanical solver
 - in case of coupled simulations the weld path is continuously updated
- possibility to define weld aiming direction based on surface normal
- provide a list of pre-defined equivalent heat sources
- use “sub-timestep” for integration of heat source for smooth temperature fields
- implementation for solid and thermal thick shells

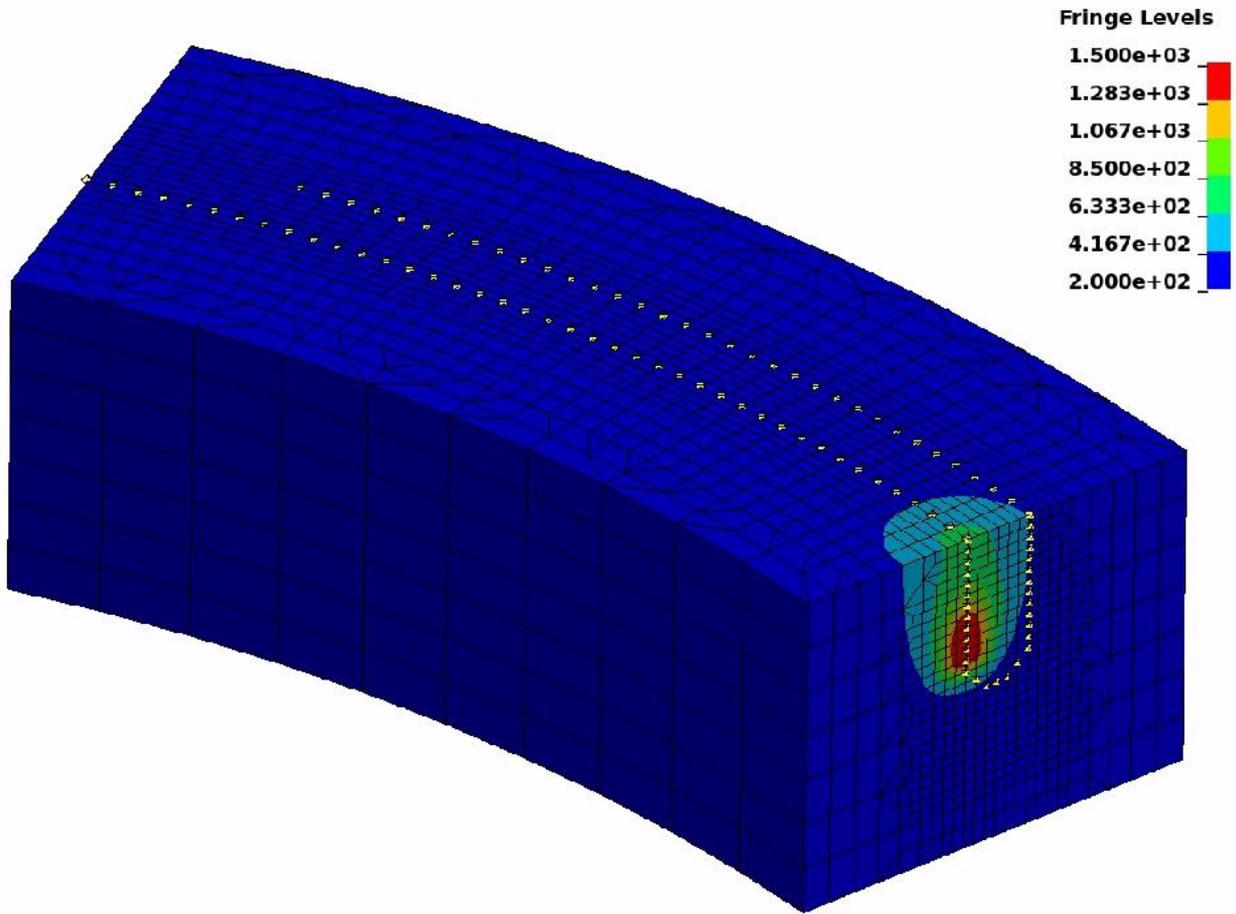
*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	RELVEL
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8
Opt.	Tx	Ty	Tz					

- **NSID1:** Node set ID defining the trajectory
- **VEL1:** Velocity of weld source on trajectory
 - LT.0: |VEL1| is load curve ID for velocity vs. time
- **SID2:** Second set ID for weld beam direction
 - GT.0: S2ID is node set ID, beam is aimed from these reference nodes to trajectory
 - EQ.0: beam aiming direction is (Tx, Ty, Tz)
 - LT.0: SID2 is segment set ID, weld source is orthogonal to the segments
- **VEL2:** Velocity of reference point for SID2.GT.0
- **NCYC:** number of sub-cycling steps

*BOUNDARY_THERMAL_WELD_TRAJECTORY

■ Example: Trajectory definition

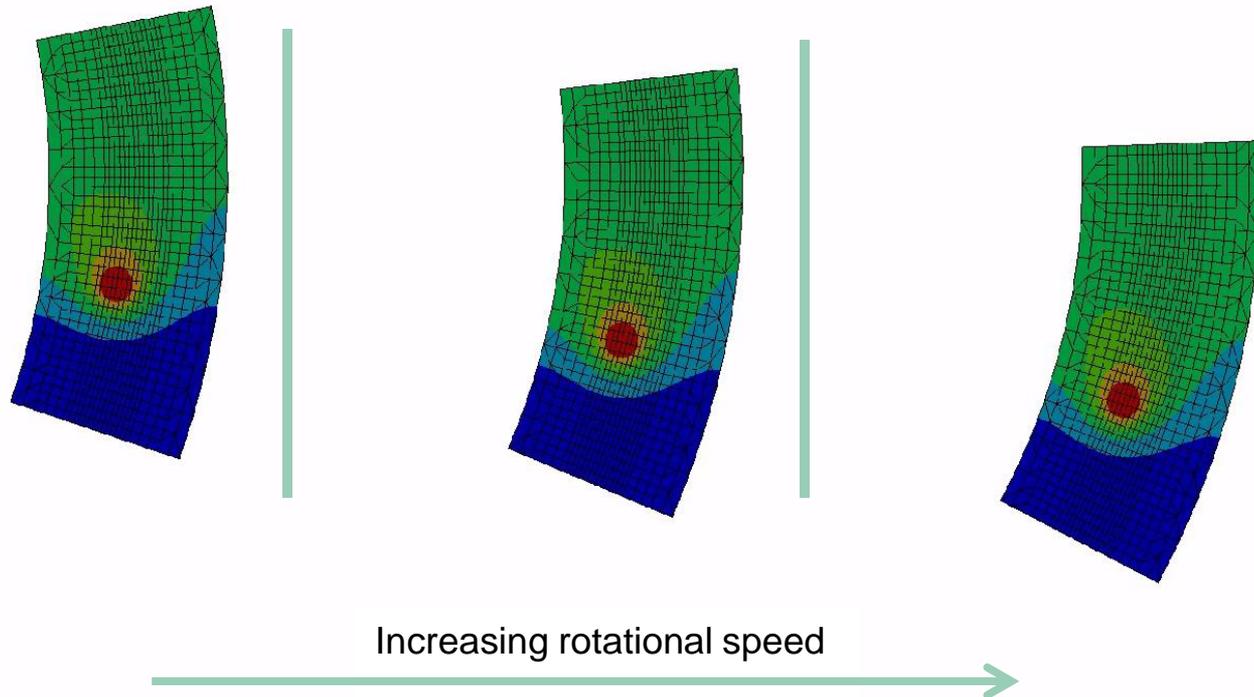


*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	RELVEL

■ RELVEL: Use relative or absolute velocities in coupled simulations

RELVEL=1

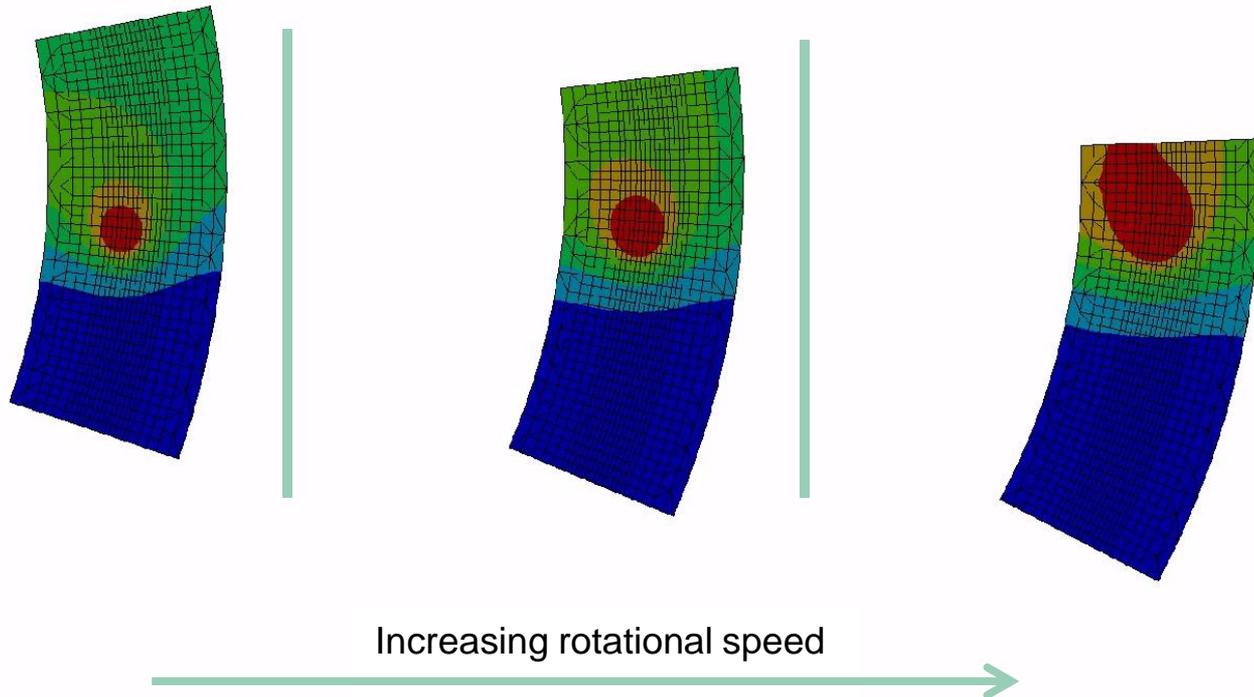


*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 1	PID	PTYP	NSID1	VEL1	SID2	VEL2	NCYC	RELVEL

- RELVEL: Use relative or absolute velocities in coupled simulations

RELVEL=0



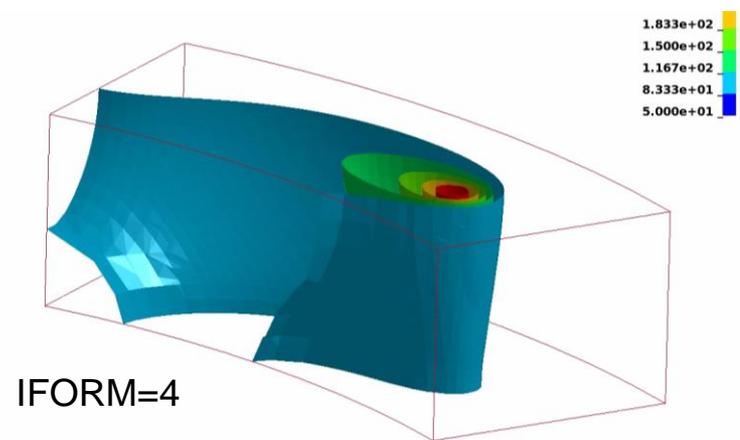
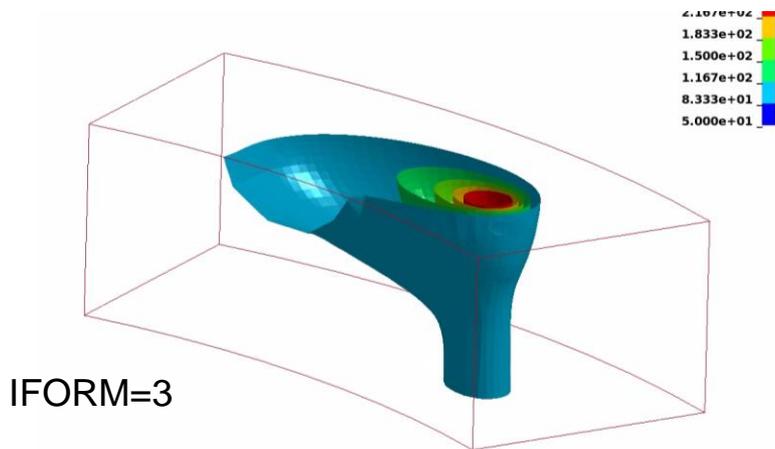
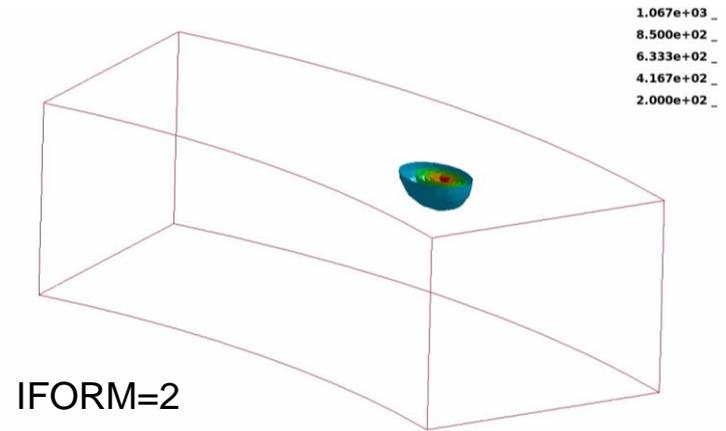
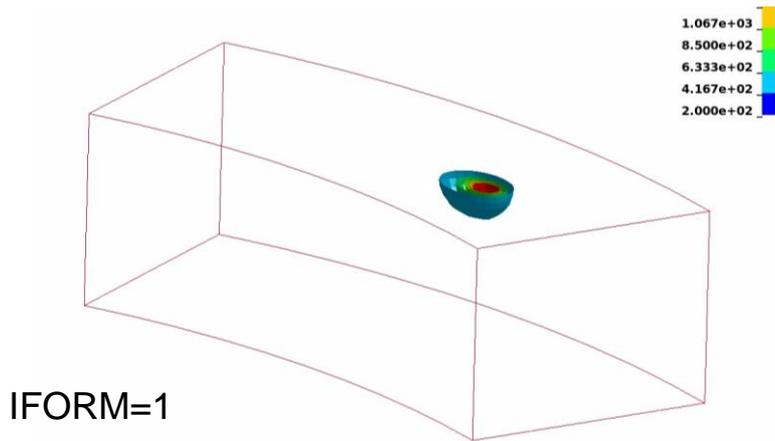
*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	
Card 3	P1	P2	P3	P4	P5	P6	P7	P8

- **IFORM:** Geometry for energy rate density distribution
 - EQ.1. Goldak-type heat source
(double ellipsoidal heat source with Gaussian density distribution)
 - EQ.2. double ellipsoidal heat source with constant density
 - EQ.3. double conical heat source with constant density
 - EQ.4. conical heat source
 - EQ.5. user-defined (*DEFINE_FUNCTION)

- **Px:** Parameters for weld pool geometry

*BOUNDARY_THERMAL_WELD_TRAJECTORY



*BOUNDARY_THERMAL_WELD_TRAJECTORY

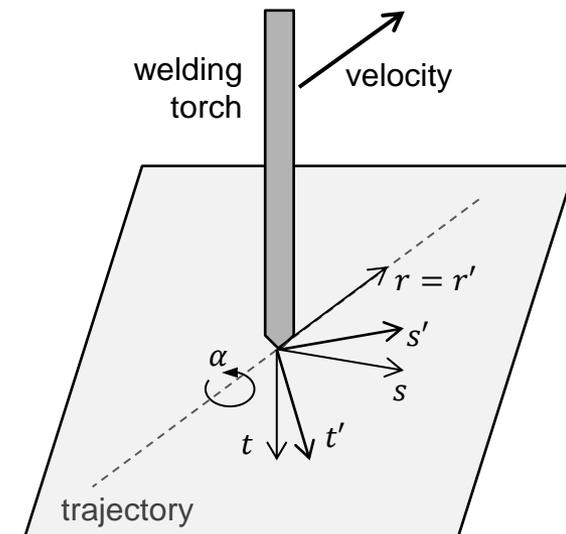
	1	2	3	4	5	6	7	8
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	

- LCID: Load curve ID for weld energy input rate vs. time
 - EQ.0: use constant multiplier value Q
- Q: Curve multiplier for weld energy input
 - LT.0: use multiplier value |Q| and accurate integration of heat
- DISC: Resolution for accurate integration. Edge length for cubic integration cells
 - Default: $0.05 \cdot (\text{weld source depth})$

*BOUNDARY_THERMAL_WELD_TRAJECTORY

	1	2	3	4	5	6	7	8
Card 2	IFORM	LCID	Q	LCROT	LCMOV	LCLAT	DISC	

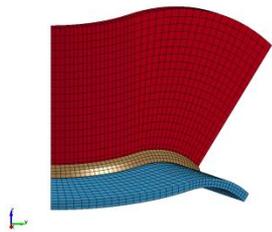
- LCROT: load curve defining the rotation (α in degree) of weld source around the trajectory as function of time.
- LCMOV: load curve for offset of weld source in depth (t') after rotation as function of time
- LCLAT: load curve for lateral offset (s') after rotation as function of time



Test example

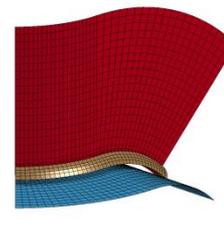
- New Keyword is applicable to thermal thick shells / mixed discretizations
- Three-dimensional curved T-Joint, thermal-only analysis

LS-DYNA keyword deck by LS-PrePost
Time = 0



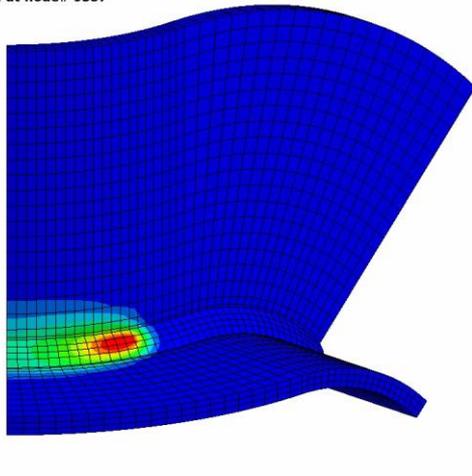
Solids

LS-DYNA keyword deck by LS-PrePost
Time = 0



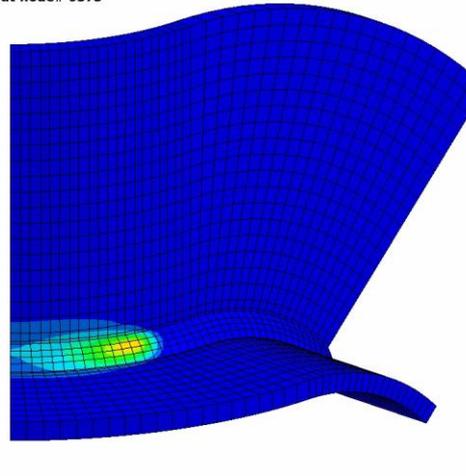
Solids and shells

LS-DYNA keyword deck by LS-PrePost
Time = 0.99484
Contours of Temperature, outer
min=19.9881, at node# 9540
max=153.564, at node# 9357



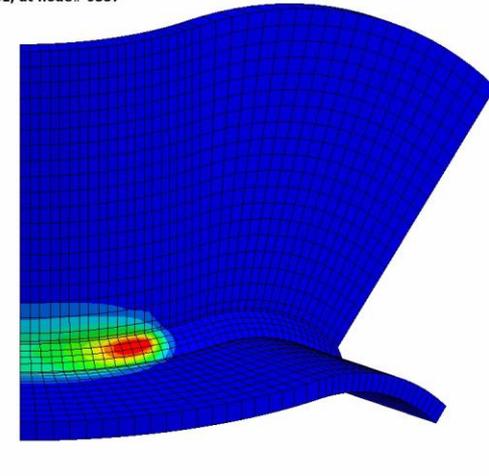
BC on all solids

LS-DYNA keyword deck by LS-PrePost
Time = 0.99484
Contours of Temperature, outer
min=19.9777, at node# 9535
max=123.47, at node# 9373

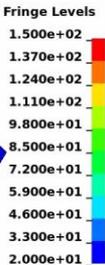


BC on solids only

LS-DYNA keyword deck by LS-PrePost
Time = 0.99484
Contours of Temperature, outer
min=19.9634, at node# 9535
max=154.901, at node# 9357



BC on solids and shells



CONTENT

- Motivation

- Flexible heat source definition

- Material formulations for welding simulations
 - *MAT_THERMAL_CWM / *MAT_T07
 - *MAT_CWM / *MAT_270
 - *MAT_UHS_STEEL / *MAT_244
 - *MAT_GENERALIZED_PHASECHANGE / *MAT_254

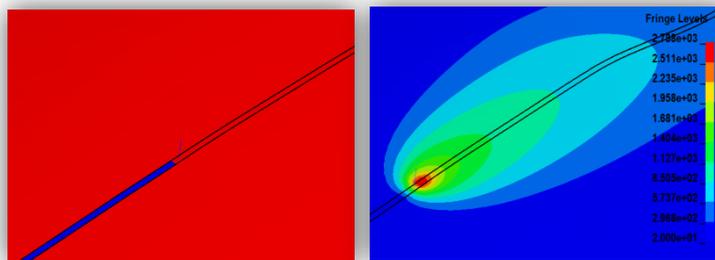
- New contact options in LS-DYNA

- Conclusion

*MAT_THERMAL_CWM / *MAT_T07

	1	2	3	4	5	6	7	8
Card 1	TMID	TRO	TGRLC	TGRMULT	HDEAD	TDEAD		
Card 2	LCHC	LCTC	TLSTART	TLEND	TISTART	TIEND	HGHOST	TGHOST

- Material has birth time TISTART and TIEND
- Before birth, HDEAD and TDEAD are used
- After birth, material is in a “Ghost” state until activated between TLSTART and TLEND
- All input for activated material is temperature dependent
- TGR stands for thermal generation rate



activation

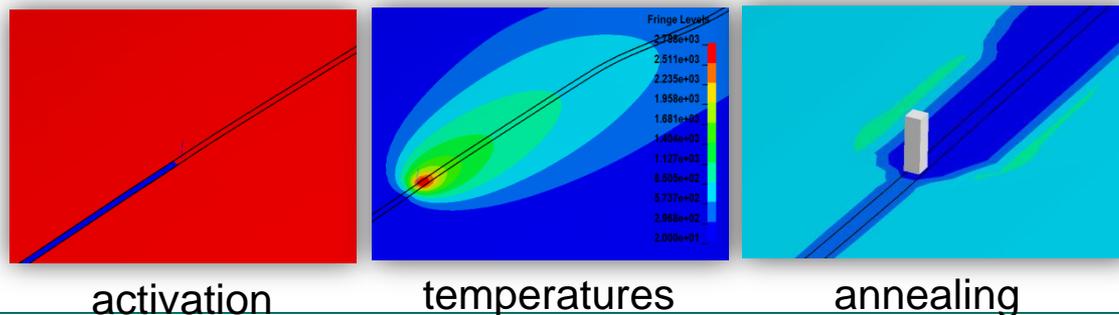
temperatures

*MAT_CWM / *MAT_270

■ Material had two different states

- Elements are initially "Ghost" or "Silent" until activated at a specific temp.
 - Low stiffness
 - Negligible thermal expansion
- After activation, material with temperature dependend
 - Mechanical properties
 - Von-Mises plasticity with mixed isotropic/kinematic hardening
 - Thermal expansion

■ Anneal at specific temperature



*MAT_CWM / *MAT_270

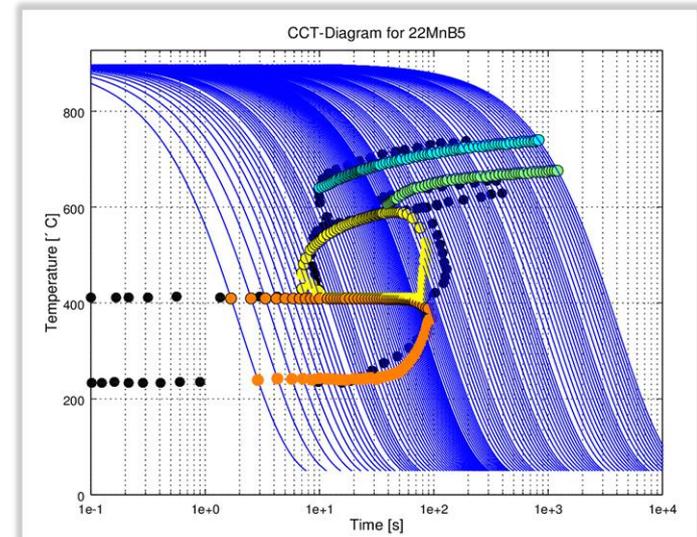
	1	2	3	4	5	6	7	8
Card 1	MID	RO	LCEM	LCPR	LCSY	LCHR	LCAT	BETA
Card 2	TASTART	TAEND	TLSTART	TLEND	EGHOST	PGHOST	AGHOST	
Opt.	T2PHASE	T1PHASE						

- Card1 contains properties for activated material
- TASTART and TAEND define range for annealing (linear process)
- TLSTART and TLEND define range for activation
- EGHOST, PGHOST and AGHOST are properties for ghost material
- T2PHASE and T1PHASE define temperature range for which the cooling rate is evaluated and stored in HISV11

***MAT_270 is well-suited to predict residual distortions but does not account for micro-structure evolution**

Status Quo: *MAT_UHS_STEEL/*MAT_244

- Material tailored for hot stamping / press hardening processes
 - Phase transition of austenite into ferrite, pearlite, bainite and martensite for cooling
 - Strain rate dependent thermo-elasto-plastic properties defined for individual phases
 - Transformation induced plasticity algorithm
 - Re-austenitization during heating
 - User input for microstructure computations is chemical composition alone
- Added:
 - Transformation induced strains
 - Welding functionality
 - Different transformation start temperatures for heating and for cooling



***MAT_244 is only valid for a narrow range of steel alloys!**

Heuristic formulas connecting chemistry with mechanics fail otherwise!

*MAT_254 / *MAT_GENERALZE_PHASE_CHANGE

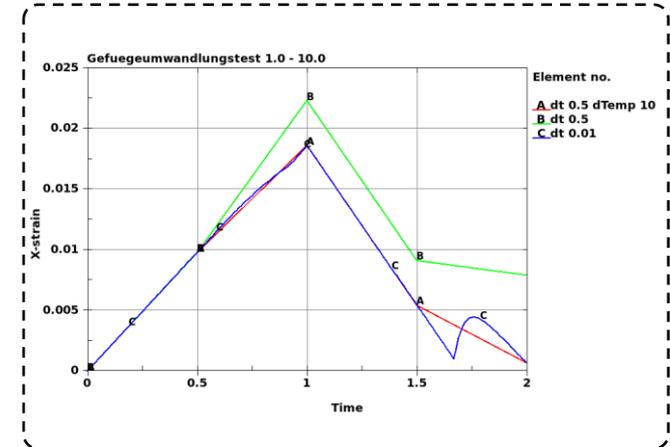
- Very general material implementation to capture micro-structure evolution in hot forming, welding and heat treatment
- Implementation available for solid and shell elements and for explicit and implicit simulations
- Microstructural phase evolution:
 - Up to 24 individual phases can be accounted for
 - List of generic phase change mechanisms (Leblond, JMAK, Koistinen-Marburger,...) for each possible phase change in heating and cooling
 - Parameters for transformation law are directly given in tables
- Additional features:
 - Strain rate dependent thermo-elasto-plastic properties defined for individual phases
 - Transformation induced plasticity and strains and latent heat
 - User-defined history variables as functions of current state of the material using DEFINE_FUNCTION keyword (e.g. for hardness, damage estimation, ...)

*MAT_254 / *MAT_GENERALIZED_PHASE_CHANGE

	1	2	3	4	5	6	7	8
Card 1	MID	RHO	N	E	PR	MIX	MIXR	
Card 2	TASTART	TAEND	TABCTE				DTEMP	
Card 3	PTLAW	PTSTR	PTEND	PTX1	PTX2	PTX3	PTX4	PTX5
Card 4	PTTAB1	PTTAB2	PTTAB3	PTTAB4	PTTAB5			
Card 5	PTEPS	TRIP			NUSHIS	GRAI	T1PHAS	T2PHAS
Card 6	FUNUSH1	FUNUSH2	FUNUSH3	FUNUSH4	FUNUSH5	FUNUSH6	FUNUSH7	FUNUSH8
Card 7	LCY1	LCY2	LCY3	LCY4	LCY5	LCY6	LCY7	LCY8
Card 8	LCY9	LCY10	LCY11	LCY12	LCY13	LCY14	LCY15	LCY16
Card 9	LCY17	LCY18	LCY19	LCY20	LCY21	LCY22	LCY23	LCY24

*MAT_254 / *MAT_GENERALIZED_PHASE_CHANGE

	1	2	3	4	5	6	7	8
Card 1	MID	RHO	N	E	PR	MIX	MIXR	
Card 2	TASTART	TAEND	TABCTE				DTEMP	
Card 3	PTLAW	PTSTR	PTEND	PTX1	PTX2	PTX3	PTX4	PTX5
Card 4	PTTAB1	PTTAB2	PTTAB3	PTTAB4	PTTAB5			
Card 5	PTEPS	TRIP			NUSHIS	GRAI	T1PHAS	T2PHAS
Card 6	FUNUSH1	FUNUSH2	FUNUSH3	FUNUSH4	FUNUSH5	FUNUSH6	FUNUSH7	FUNUSH8
Card 7	LCY1	LCY2	LCY3	LCY4	LCY5	LCY6	LCY7	LCY8
Card 8	LCY9	LCY10	LCY11	LCY12	LCY13	LCY14	LCY15	LCY16
Card 9	LCY17	LCY18	LCY19	LCY20	LCY21	LCY22	LCY23	LCY24



Selected mechanical features

- temperature dependent elastic properties
- yield stress (van Mises) temperature and strain rate dependent
- transformation induced strains and transformation induced plasticity
- reset of plastic strains in a certain temperature range
- sub-cycling on integration point level to deal with large temperature rates

*MAT_254 / *MAT_GENERALIZED_PHASE_CHANGE

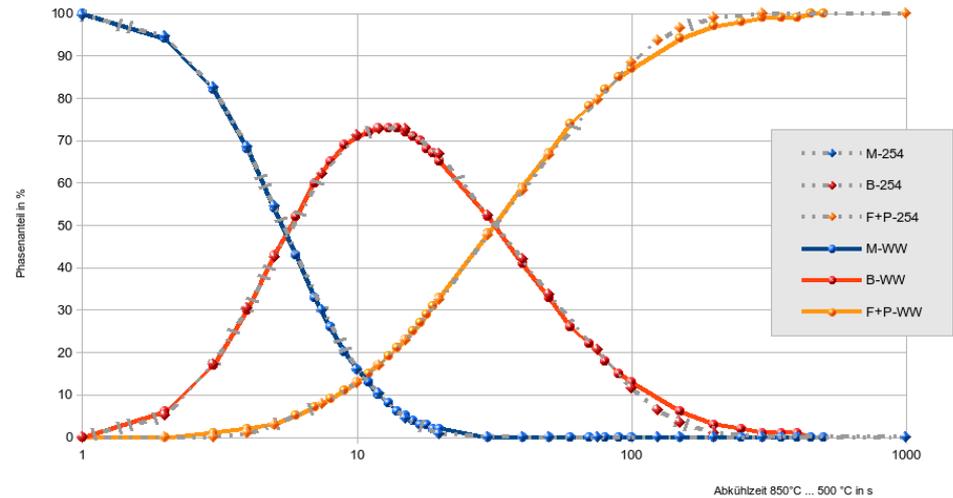
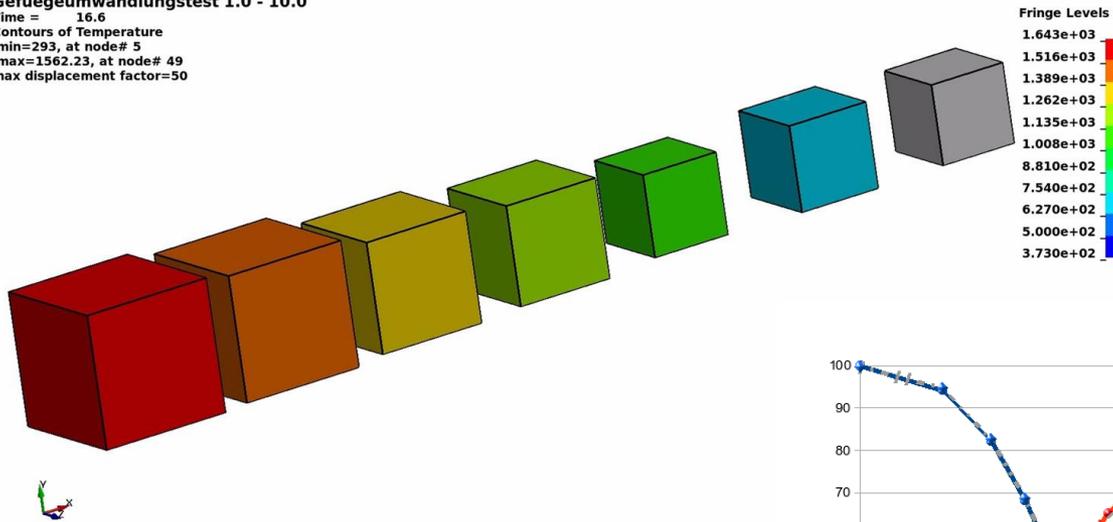
	1	2	3	4	5	6	7	8
Card 3	PTLAW	PTSTR	PTEND	PTX1	PTX2	PTX3	PTX4	PTX5
Card 4	PTTAB1	PTTAB2	PTTAB3	PTTAB4	PTTAB5			

- **PTLAW:** Table ID containing phase transformation laws
 - If law ID.GT.0: used for cooling
 - If law ID.LT.0: used for heating
 - |LAW ID|:
 - EQ.1: Koistinen-Marburger
 - EQ.2: JMAK
 - EQ.3: Kirkaldy (only cooling)
 - EQ.4: Oddy (only heating)
- **PTSTR:** Table ID containing start temperatures
- **PTEND:** Table ID containing end temperature
- **PTX i :** i -th scalar parameter (2D table input)
- **PTTAB i :** i -th temperature dependent parameter (3D table input)

*MAT_254 with JMAK

■ First example: Phase change test for steel S420

Gefügeumwandlungstest 1.0 - 10.0
Time = 16.6
Contours of Temperature
min=293, at node# 5
max=1562.23, at node# 49
max displacement factor=50



*MAT_254 / *MAT_GENERALIZED_PHASE_CHANGE

Card 5	PTEPS	TRIP			NUSHIS	GRAI	T1PHAS	T2PHAS
Card 6	FUNUSH1	FUNUSH2	FUNUSH3	FUNUSH4	FUNUSH5	FUNUSH6	FUNUSH7	FUNUSH8

- NUSHIS: Number of user defined history variables
- FUNUSH*i*: Function ID
- T1PHAS: lower temperature limit for cooling rate computation
- T2PHAS: upper temperature limit for cooling rate computation
- User defined histories:
 - written as additional histories for output
 - can be defined as function of other history data
time, temp, temp rate, stresses, phase mixture, plastic strains, ...

CONTENT

- Motivation

- Flexible heat source definition

- Material formulations for welding simulations

- New contact options in LS-DYNA
 - Temperature activated tied contact
 - Thermal shell edge contact

- Conclusion

*CONTACT__AUTOMATIC_SURFACE_TO_SURFACE__TIED_WELD_THERMAL

	1	2	3	4	5	6	7	8
Card 4	TEMP	CLOSE	HWELD					
Card 5	K	Hrad	H0	LMIN	LMAX	CHLM	BC_FLAG	ALGO

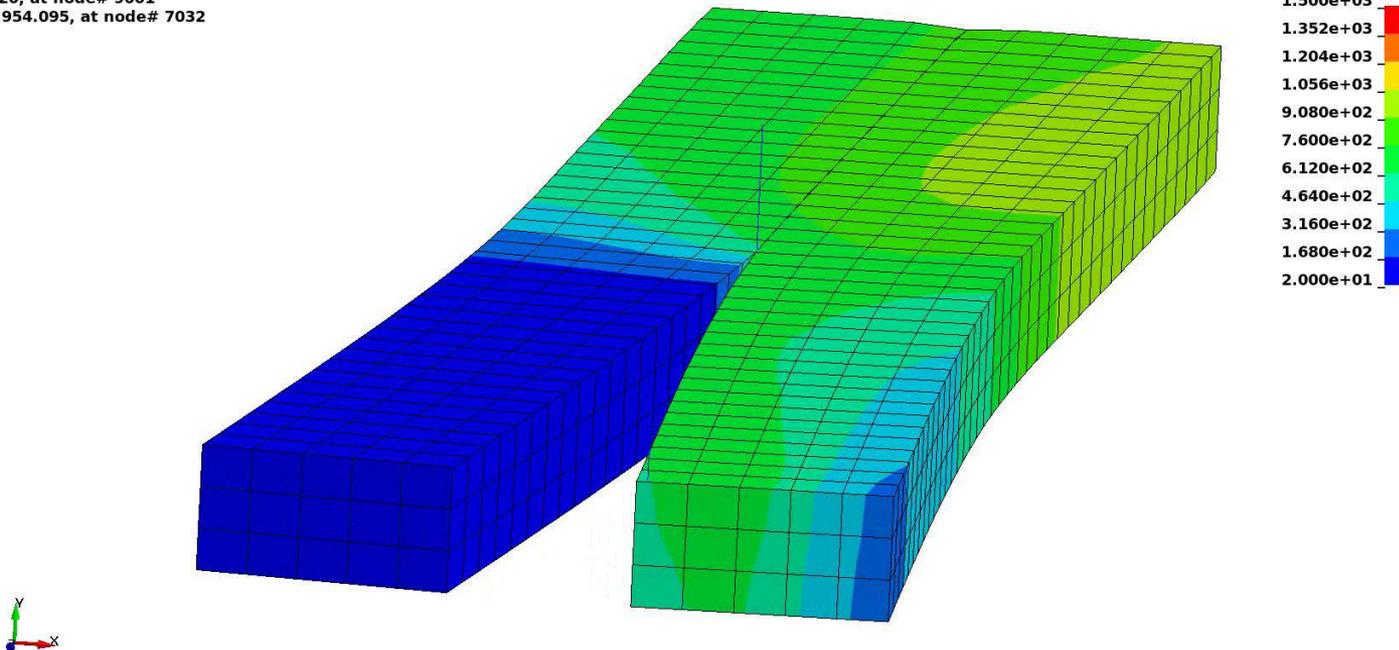
- Contact that can locally switch from a sliding to a tied formulation
- Card4 is read if TIED_WELD is set
 - TEMP: Welding temperature
 - CLOSE: maximum contact gap for which tying is considered
 - HWELD: Heat transfer coefficient for welded regions
- Card5 is standard for THERMAL option
 - H0: Heat transfer coefficient for unwelded regions
- MORTAR version also available and recommended

*CONTACT__AUTOMATIC_SURFACE_TO_SURFACE__TIED_WELD_THERMAL

■ Example: butt weld

- During welding the blocks are allowed to move
- Assumption: Insulation in unwelded state, perfect heat transfer after welding

welding_contact_automatic_tied_weld_thermal.k
Contours of Temperature
min=20, at node# 9001
max=954.095, at node# 7032

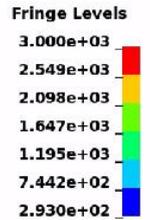
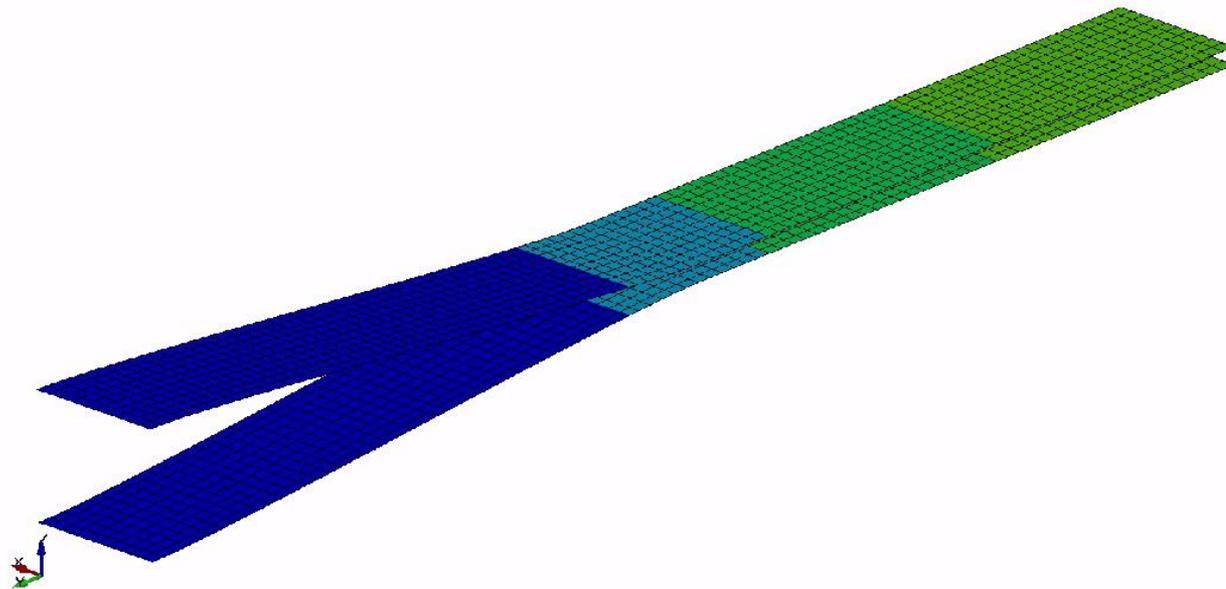


*CONTACT__AUTOMATIC_SURFACE_TO_SURFACE__TIED_WELD_THERMAL

■ Example: laser welding

- During welding the sheets are allowed to move
- A very high heat conductivity in the contact area is assumed

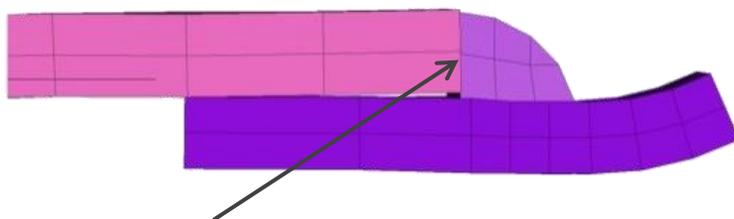
Time = 9.0292



Thermal edge contact

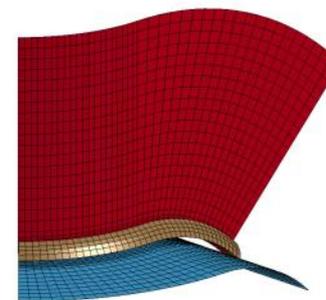
	1	2	3	4	5	6	7	8
Card	K	Hrad	H0	LMIN	LMAX	CHLM	BC_FLAG	ALGO

- Certain scenarios require to consider heat transfer across the edge of a shell into a surface:



Coupling of a sheet metal to a weld seam

LS-DYNA keyword deck by LS-PrePost
Time = 0

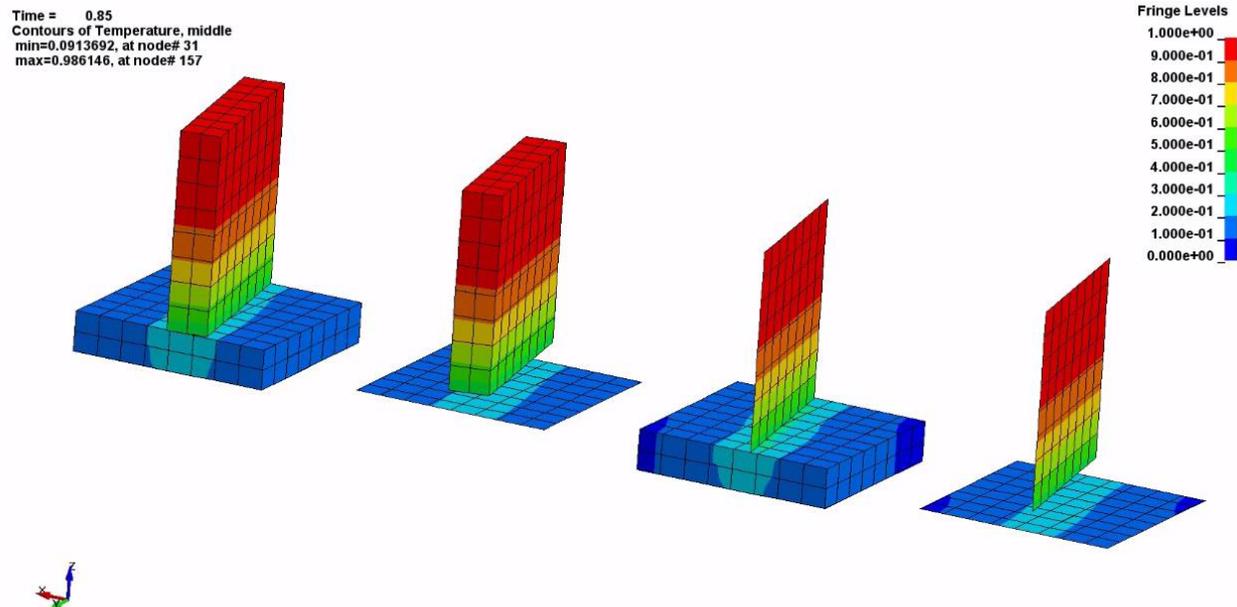


T-Joint with shells

- Activated for ALGO.eq.2 or 3 (one way)
- Can be used in a variety of contact types in SMP and MPP

Thermal edge contact – Example

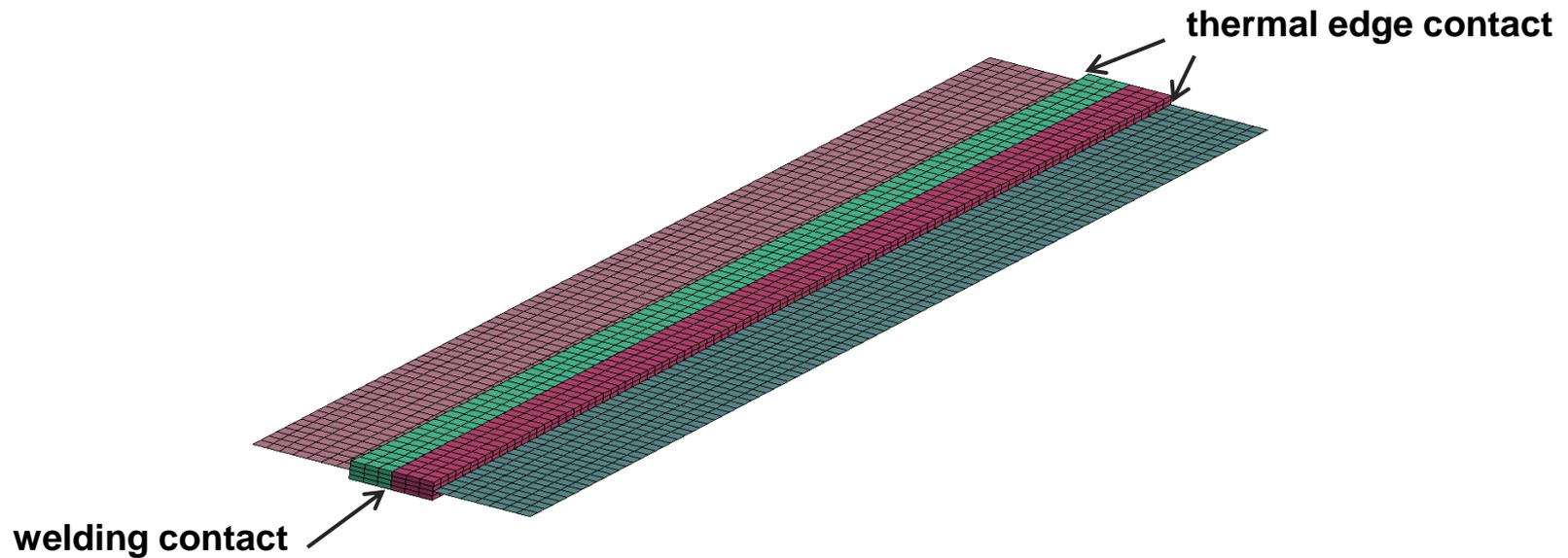
- Thermal only-analysis of heat transfer across a rotated T-joint
- Two-way contact
- Comparison of different discretization approaches for both parts (solid to shell, solid to shell, shell to solid, shell to shell)





Thermal edge contact + welding contact - Example

- Laser welding of a butt weld of a shell structure
- Welded area discretized with solids
- Shell elements tied to the solid elements

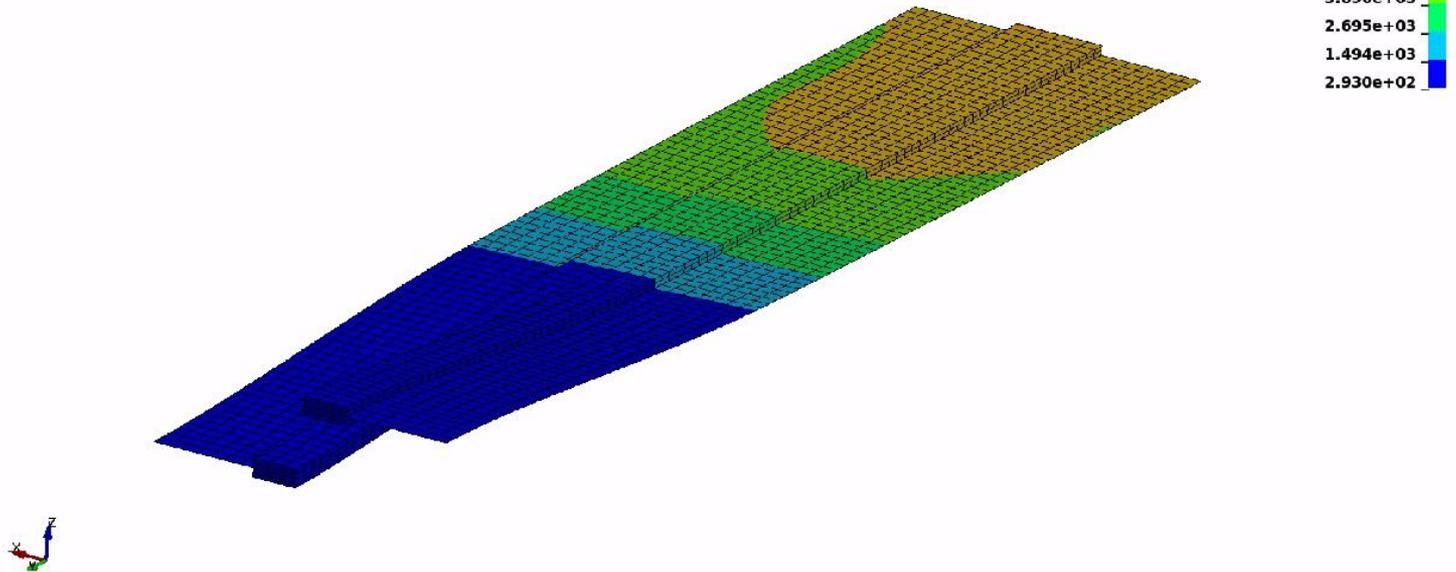




Thermal edge contact + welding contact - Example

- Laser welding of a butt weld of a shell structure
- Welded area discretized with solids
- Shell elements tied to the solid elements

Time = 7.4292



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Conclusion

■ *BOUNDARY_THERMAL_WELD_TRAJECTORY

- Realistic description of the heat source for all fusion welding processes and local heat treatment
- Easy and flexible input also for curved and deforming structures
- Readily applicable as tool in the virtual process chain even with mixed discretizations

■ *MAT_GENERALIZED_PHASECHANGE

- General material formulation accounting for microstructure evolution
- Very flexible input structure
- Valid description for a wide range of steel alloys

■ New contact formulations

- Welding contact for solids and shell, featuring a switch from sliding to tied contact activated by the temperature
- Edge contact for heat transfer between shell edges and surfaces

Thank you
for your attention!

Many thanks to
Mikael Schill (DYNAmore Nordic) and
Tobias Loose (Ingenieurbüro Loose)!

